

Hamiltonian Lie algebras: physical applications and cohomological descriptions

1. Introduction

o Momentum maps

(M, ω) symplectic manifold

Lie group $G \curvearrowright M$ induces $\mathfrak{g}: \mathfrak{g} \rightarrow TM$

$\mathfrak{g}$: Lie algebra of G

map $\mu: M \rightarrow \mathfrak{g}^*$ is called a momentum map

$$1. \quad d\mu(e) = -\iota_{\mathfrak{g}(e)}\omega \quad \langle \mu, e \rangle = \mu(e)$$

$\langle \cdot, \cdot \rangle$ pairing of $\mathfrak{g}$ & $\mathfrak{g}^*$ $e \in \mathfrak{g}$

$\mathfrak{g}: \mathfrak{g} \rightarrow TM$; infinitesimal action of $\mathfrak{g}$

2. equivariant

$$\langle \mu(g \cdot p), e \rangle = \langle \mu(p), \text{Ad}_{g^{-1}} \cdot e \rangle$$

for $\forall p \in M, \forall e \in \mathfrak{g}$

infinitesimally

$$\iota_{\mathfrak{g}(e_1)}\mu(e_2) = \mu(\text{ad}_{e_1}(e_2)) = \mu([e_1, e_2])$$

for $\forall e_1, e_2 \in \mathfrak{g}$

1. Generalizations to Lie algebras

2. $E = M \times \mathfrak{g}$ Lie spd

$$\mu \in \mathcal{P}(E^*) = \mathcal{P}(M \times \mathfrak{g}^*)$$

→ generalization to A Lie algebras

Def A Lie algebroid E is a vector bundle over a smooth manifold M ,
equipped with a bundle map

$\rho: E \rightarrow TM$
and a Lie bracket,

$$[-, -]: \Gamma(E) \times \Gamma(E) \rightarrow \Gamma(E)$$

satisfying the Leibniz rule

$$[e_1, f e_2] = f [e_1, e_2] + (\rho(e_1) f) e_2$$

for all $e_1, e_2 \in \Gamma(E)$, $f \in C^\infty(M)$.

$(A, \rho, [-, -])$ is called a Lie algebroid.

Ex. G/M Lie group action

induces $\rho: M \times \mathfrak{g} \rightarrow TM$ infinitesimal Lie algebra action

$$\text{s.t. } [\rho(e_1), \rho(e_2)] = \rho([e_1, e_2]) \quad e_1, e_2 \in \mathfrak{g} \quad \text{d.}$$

$(E = M \times \mathfrak{g}, [-, -], \rho)$ is called an action Lie algebroid

Def A Lie algebroid differential (E-differential)
 $\mathbb{E}_d$ on $\Gamma(\wedge^* E^*)$

For $\eta \in \Gamma(\wedge^m E^*)$ $L_{\rho(e_i)} \eta$

$$\begin{aligned} \mathbb{E}_d \eta(e_1, \dots, e_{m+1}) &= \sum_{i=1}^{m+1} (-1)^{i-1} \rho(e_i) \eta(e_1, \dots, \check{e}_i, \dots, e_{m+1}) \\ &\quad + \sum_{1 \leq i < j \leq m+1} (-1)^{i+j} \eta([e_i, e_j], e_1, \dots, \check{e}_i, \dots, \check{e}_j, \dots, e_{m+1}) \end{aligned}$$

$$(\mathbb{E}_d)^2 = 0$$

Def A connection on E is a $\mathbb{R}$ -linear map

$$\nabla: \Gamma(E) \rightarrow \Gamma(E \otimes T^*M) \text{ satisfying}$$

$$\nabla(fe) = f(\nabla e) + df \otimes e$$

for $e \in \Gamma(E)$, $f \in C^\infty(M)$.

Def Let E be a Lie algebroid.

An E -connection on E' is a $\mathbb{R}$ -linear map

$\nabla: \mathcal{P}(E') \rightarrow \mathcal{P}(E' \otimes E^*)$ satisfying

$$\nabla_e(fe') = f(\nabla_e e') + (f(e)f')e'$$

$$e \in \mathcal{P}(E), e' \in \mathcal{P}(E') \quad f \in C^\infty(M)$$

Remark The connection ∇ is TM -connection $\nabla = TM \nabla$.

Def Let E be a Lie algebroid equipped with a connection ∇ .

The basic E -connection on TM is

$$\nabla_e^{\text{bas}} v := \mathcal{L}_{f(e)} v + f(\nabla_v e) = [f(e), v] + f(\nabla_v e)$$

Remark The basic E -connection on E

$$\nabla_e^{\text{bas}} e' := \nabla_{f(e)} e' + [e, e']$$

2. Hamiltonian Lie algebrads

Def Let (M, ω) be a pre-symplectic manifold.

$$\omega \in \Omega^2(M), \quad d\omega = 0$$

Let $E \rightarrow M$ be a Lie algebrad (E, ∇, ρ)

(S1) E is pre-symplectically anchored if

$$E \nabla \omega = 0$$

(S2) A section $P(A^*)$ is a momentum section if it satisfies

$$(\nabla_\mu)(e) = - \iota_{\rho(e)} \omega$$

(S3) μ is called bracket compatible if

$$(E d\mu)(e_1, e_2) = - \iota_{\rho(e_1)} \iota_{\rho(e_2)} \omega$$

for $e, e_1, e_2 \in P(E)$

If (E, M, ω) has (∇, μ) satisfying (S1) (S2) (S3), E is called

Hamiltonian.

Prop Let $E = M \times \mathfrak{g}$ be an action Lie algebrad

Then momentum section μ is a momentum map.

Hamiltonian Lie algebrad is a Ham. $\mathfrak{g}$ -space

Proof We can choose $\nabla = d$ deRham differential

$$(S1) \Leftrightarrow d\omega = 0$$

$$(S2) \Leftrightarrow d\mu(e) = -\mathcal{L}_g(e)\omega$$

$\mu(e)$ hamiltonian

$$(S3) \text{ under (S2)} \Leftrightarrow \mathcal{L}_{g(e)}\mu(e_2) = \mu([e_1, e_2]) \text{ equivariant} \quad \square$$

$$\begin{aligned} & (S3) \quad (\bar{E}d\mu)(e_1, e_2) \\ &= \mathcal{L}_{g(e_1)}\mu(e_2) - \mathcal{L}_{g(e_2)}\mu(e_1) - \mu([e_1, e_2]) \\ &= -\mathcal{L}_{g(e_1)}\mathcal{L}_{g(e_2)}\omega \quad \text{--- ①} \end{aligned}$$

$$(S2) \times \mathcal{L}_g$$

$$\mathcal{L}_{g(e_1)}\mu(e_2) = -\mathcal{L}_{g(e_1)}\mathcal{L}_{g(e_2)}\omega \quad \text{--- ②}$$

$$\text{①} + \text{②}$$

$$\begin{aligned} \mathcal{L}_{g(e_1)}\mu(e_1) &= -\mu([e_1, e_2]) \\ &= \mu([e_2, e_1]) \quad // \end{aligned}$$

3. Examples in physics

Example Hamiltonian mechanics

M : smooth manifold

g_i metric

T^*M wcan (x^i, p_i) $\omega = dx^i \wedge dp_i$

E vector bundle on M
 $\downarrow$
 M

$pr^*E \xrightarrow{pr^*} E$
 $\downarrow \quad \downarrow$
 $T^*M \xrightarrow{pr} M$

Hamiltonian $H = \frac{1}{2} g^{ij}(x) p_i p_j$

$g^{ij}(x) : g^{-1}$

constraints $G = G_a(x, p) e^a \in \Gamma(pr^*E^*)$

$G_a = g_a^i(x) p_i$

$e^a \in \Gamma(E^*)$

consistency conditions

① $\{H, H\} = 0$

② $\{H, G_a\} = \gamma_a^b(x, p) G_b$

③ $\{G_a, G_b\} = C_{ab}^c(x) G_c$

$\left. \begin{matrix} \text{①} \\ \text{②} \\ \text{③} \end{matrix} \right\} \textcircled{*}$

③ We obtain two operators on E

$\mathcal{G} = g_a^i(x) e^a \partial_i : E \rightarrow TM$ anchor

$[e_a, e_b] = C_{ab}^c(x) e_c \quad e_a \in \Gamma(E)$

③ gives $[g(e_1), g(e_2)] = g([e_1, e_2])$

E is an almost Lie algebroid

Jacobi of ③ $\Leftrightarrow$ Jacobiator of $G, \nabla \in \mathcal{K}_A(\text{Im } p)$
 $\Leftarrow E$ is a Lie algebra $\left\{ \begin{array}{l} \text{Courant algebra} \\ (\text{L n-algebra}) \text{ Leibniz algebra} \end{array} \right.$
 bilinear bracket

Assume that E is a Lie algebra.
 Then G, ∇ is a Lie bracket.

② $\delta_a^b(x, p) = \omega_a^b(x) p_i$ by order counting

$$G'_a = M_a^b(x) G_b$$

$M_a^b(x)$ transition function of E

$$\omega_{ai}^b = g_{ij} \omega_a^{bj} \quad \omega^i = \omega_a^i dx^a$$

$$\omega^i = M^i_j \omega^j + M^i_j dM^j$$

is a connection 1-form $\nabla = d + \omega$

$E \nabla$: basic E -connection on TM

② Jacobi $E \nabla g = 0$

Th If E with ∇ and satisfies $E \nabla g = 0$
 M is a Lie algebra

⊗ is satisfied,

Remark $\begin{array}{c} E \\ \downarrow \\ (M, g) \end{array}$ Killing Lie algebras

3-2 EM fields U(1)-connection $U(1) \rightarrow \frac{U(1)}{1} \rightarrow \frac{U(1)}{1}$

$A = A_i(x) dx^i$ U(1)-connection 1-form on M

$$P'_i = p_i - A_i$$

$$H' = \frac{1}{2} g^{ij} (p_i - A_i) (p_j - A_j) = \frac{1}{2} g^{ij} p'_i p'_j + V(x)$$

$$G'_a = p'_a(x) (p_i - A_i) + \mu_a(x) = p'_a p'_i + \mu_a$$

$$\mu = \mu_a(x) e^a \in T^*(E^*)$$

Then $\{x^i, x^j\} = 0$

$$\{x^i, p'_j\} = \delta^i_j$$

$$\{p'_i, p'_j\} = F_{ij}(x)$$

$$F = dA \in \Omega^2(M)$$

obviously $dF = 0$

F presymplectic form on M

We impose

$$\{H', H'\} = 0$$

$$\{H', G'_a\} = g^{ij} \omega_{aj}^b(x) p'_i G'_b$$

$$\{G'_a, G'_b\} = C_{ab}^c(x) G'_c$$

Assume that E is a Lie algebra

$$\begin{matrix} E \\ \nabla \end{matrix}$$

$\omega_{aj}^b dx^i$ connection 1-form

under this assumption.

new ones $\mu, F = dA$

Th [NI'19]

Let E is a Klt Lie algebroid.

$$(E \text{ Lie algebroid} + E \nabla g = 0)$$

Then iff E is Hamiltonian Lie algebroid

($\mu \in P(E^*)$ is a momentum section)

(S1)(S2)(S3)

~~(*)~~ is satisfied, where $\omega = F$

4. Cohomological description of HLA

BFV formalism

$$N = T^*E[G] \quad \text{with} \quad \omega_{N \text{ can}} \quad |\omega_{N \text{ can}}| = 0$$

$$\begin{pmatrix} \chi^i & p_i & c^a & b_a \\ 0 & 0 & 1 & -1 \end{pmatrix} = \delta \chi^i \wedge \delta p_i + \delta c^a \wedge \delta b_a$$

BFV charge & BFV Ham degree (1,0)

$$S, \{ \text{~~***~~ \} } S_{\text{BFV}}, S_{\text{BFV}} \} = \{ S_{\text{BFV}}, H_{\text{BFV}} \} = \{ H_{\text{BFV}}, H_{\text{BFV}} \} = 0$$

$$S_{\text{BFV}} = \underbrace{c^a G_{Ta}}_{\text{Lie algebra}} - \frac{1}{2} C_{ab} \underbrace{\chi^a \chi^b}_{\text{Lie algebra}} b_b + \dots$$

$$H_{\text{BFV}} = H + \underbrace{\omega_a^{bi} p_i}_{\gamma} c^a b_b + \dots$$

$$p_i^{\gamma} = p_i - \omega_{ai}^b c^a b_b \quad \text{covariantized momentum}$$

$$= \frac{1}{2} g^{ij} p_i^{\gamma} p_j^{\gamma} + \frac{1}{2} U_{ab}^{cd} (g_c) C^a C^b b_c b_d$$

Def $U \in P(\wedge^2 E^* \otimes \wedge^2 E)$ (2,2) tensor

Th If U satisfies

$$\left(\begin{smallmatrix} NE \\ \text{stab} \end{smallmatrix} \right)^{\gamma} \langle U, \gamma \rangle = E_S$$

$$E \nabla U + E^T U = 0$$

~~***~~ holds.

2 Geometric quantities

$$v, v' \in \mathcal{X}(M), \quad e, e' \in \Gamma(E)$$

$$\left(\begin{array}{l} \text{curvature} \quad R \in \Omega^2(M, E \otimes E') \\ R(v, v') := [\nabla_v, \nabla_{v'}] - \nabla_{[v, v']} \\ \text{E-curvature} \quad {}^E R \in \Gamma(\wedge^2 E^* \otimes E \otimes E') \\ {}^E R(e, e') := [{}^E \nabla_e, {}^E \nabla_{e'}] - {}^E \nabla_{[e, e']} \\ \text{E-torsion} \quad {}^E T \in \Gamma(\wedge^2 E^* \otimes E) \end{array} \right)$$

$${}^E T(e, e') := \nabla_{g(e)} e' - \nabla_{g(e')} e - [e, e']$$

$$\text{basic curvature} \quad {}^E S \in \Omega^1(M, \wedge^2 E^* \otimes E)$$

$$\begin{aligned} {}^E S(e, e') &:= [e, \nabla e'] - [e', \nabla e] - \nabla [e, e'] \\ &\quad - \nabla_{g(e)} e' + \nabla_{g(e')} e \end{aligned}$$

$$= (\nabla A + 2A + \gamma_R)(e, e') \quad (w)$$

$$= [e, \nabla_v e'] - [e', \nabla_e e] - \nabla_v [e, e']$$

$$- \nabla_e^{\text{bas}} e' + \nabla_{e'}^{\text{bas}} e$$

Properties

$$\rho \circ \nabla^{\text{bas}} = \nabla^{\text{bas}} \circ \rho$$

$${}^E R = \rho \circ {}^E S$$

$${}^E \nabla^{\text{bas}} {}^E S = 0$$

$$[\nabla, {}^E \nabla] \alpha \sim \langle {}^E S, \alpha \rangle$$

"Branchi identity"

Cor, If $ES=0$ i.e. E is a Catalan LA,
 $U=0$ is a solution
~~AKSZ~~ has a solution.

$$\begin{array}{cc} BV & AKSZ \\ M = M_{\text{up}}(T[0,1] \mathbb{R}, N) & T[0,1] \mathbb{R} \ni (t, \theta) \end{array}$$

$$\omega_{BV} = \int_{T[0,1] \mathbb{R}} \text{td} \omega_{BFV}$$

$$S_{BV} = \int_{T[0,1] \mathbb{R}} (\text{td} (p dx^u + b a d c^a - (S_{BFV} + \theta H_{BFV})))$$

Grigoriu-Damgaard AKSZ
 BFV to BV

$$(S_{BV}, S_{BV})_{\mu} = 0$$

Remark HLA
 $\langle ES, \mu \rangle = 0$

Other examples

1. 2D GNLSM with boundary
2. 2D g PSM

HLA on Poisson Blohmann Roudi Weinstein^{'23}

HLA on pre multi-symp Hirota-NI^{'22}
n D GNLSM with WZ term Hull-Spence^{'89}

Callies, Fregier, Rogers Zambon^{'16}

HLA on CA NI^{'21}
Dirac^{'23}

HLA over multisym Hirota, NI^{'22}

A momentum map is a Poisson map

$$\begin{array}{ccc} \mu: M & \rightarrow & \mathfrak{g}^* \\ \pi & & \pi_K \end{array}$$

A momentum section is not a Poisson map,

$$\begin{array}{ccc} \mu: M & \rightarrow & \mathfrak{A}^* \\ \pi_M & & \pi_M + \pi_A \end{array}$$

$\Rightarrow$ generalizations Hirota NZ^{'24}